

# A multiplicity result for a class of elliptic boundary value problems

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## SYNOPSIS

We consider a mildly nonlinear elliptic boundary value problem depending on a parameter. Given appropriate hypotheses concerning the asymptotic behaviour of the nonlinearity, we derive lower bounds on the number of solutions. The results complement an earlier theorem due to Kazdan and Warner [6].

## I. STATEMENT OF THE RESULT

We consider the semilinear elliptic boundary value problem (*BVP*)

$$(P_t) \quad \begin{aligned} Au &= f(x, u; t) && \text{in } \Omega, \\ Bu &= 0 && \text{on } \partial\Omega, \end{aligned}$$

where  $t$  is a real parameter. Here  $\Omega$  is a bounded domain in  $R^N$  ( $N \geq 1$ ) with smooth boundary  $\partial\Omega$ , and

$$Au := - \sum_{j,k=1}^N a_{jk} D_j D_k u + \sum_{j=1}^N a_j D_j u + a_0 u$$

a second order linear elliptic differential operator with smooth real coefficients and a uniformly positive definite coefficient matrix  $(a_{jk})$ . Further  $B$  denotes either the Dirichlet or the Neumann boundary operator. Let  $\lambda_1$  be the principal eigenvalue of the linear *BVP*

$$\begin{aligned} Au &= \lambda u && \text{in } \Omega, \\ Bu &= 0 && \text{on } \partial\Omega. \end{aligned}$$

The following hypotheses are imposed on the nonlinearity  $f$ :

- (f1) the function  $f: \bar{\Omega} \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  is smooth;
- (f2) for every  $m \in \mathbb{R}$ , there exists a function  $h \in C(\bar{\Omega})$  such that  $D_3 f(x, \xi; t) \geq$

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$h(x) > 0$  for all  $x \in \Omega$ ,  $\xi \geq m$ , and  $t \in \mathbb{R}$ ;

(f3) for every  $x \in \bar{\Omega}$ ,  $t \in \mathbb{R}$ ,

$$(f3') \limsup_{\xi \rightarrow -\infty} \frac{f(x, \xi; t)}{\xi} < \lambda_1$$

and

$$(f3'') \liminf_{\xi \rightarrow +\infty} \frac{f(x, \xi; t)}{\xi} > \lambda_1,$$

uniformly for  $x \in \bar{\Omega}$  and  $t$  in bounded intervals;

$$(f4) \limsup_{\xi \rightarrow +\infty} \frac{f(x, \xi; t)}{\xi} < +\infty,$$

uniformly for  $x \in \bar{\Omega}$  and  $t$  in bounded intervals.

We are now in position to state our main result.

**THEOREM.** *Under the above hypotheses, there exists a number  $t_0 \in \mathbb{R}$  such that  $(P_t)$  has no (classical) solution if  $t > t_0$ , at least one solution if  $t = t_0$ , and at least two distinct solutions if  $t < t_0$ .*

Some remarks concerning the comparison of this result with related former research are in order.

1. It has been shown by Kazdan and Warner [6, Corollary 3.11] that hypotheses (f1)–(f3) (without the uniformity assumption with respect to  $t$ ) imply the existence of a number  $t_0 \in \mathbb{R}$  such that  $(P_t)$  has no solution if  $t > t_0$  and at least one solution if  $t < t_0$ . No multiplicity result is obtained there, and no assertion is made for  $t = t_0$ .

2. Suppose  $f$  is of the special form

$$f(x, \xi; t) = f_0(x) + tr(x) + g(x, \xi), \quad (1)$$

with  $r(x) > 0$  for  $x \in \Omega$ . Then  $f$  satisfies hypotheses (f2)–(f4) provided

$$\limsup_{\xi \rightarrow -\infty} \frac{g(x, \xi)}{\xi} < \lambda_1$$

and

$$\lambda_1 < \liminf_{\xi \rightarrow +\infty} \frac{g(x, \xi)}{\xi} \leq \limsup_{\xi \rightarrow +\infty} \frac{g(x, \xi)}{\xi} < +\infty,$$

uniformly for  $x \in \bar{\Omega}$ . In this case, besides the assertion of the Theorem, its proof further yields the closedness in  $C(\bar{\Omega})$  of the set of functions  $p$  for which the nonlinear BVP

$$\begin{cases} Au = p(x) + g(x, u) & \text{in } \Omega, \\ Bu = 0 & \text{on } \partial\Omega \end{cases}$$

has a solution. We generalize the result of Ambrosetti and Prodi [3] and Berger and Podolak [4]. Recall that in [4], for formally selfadjoint  $A$ , with  $B$  the Dirichlet boundary operator,  $g(x, \xi) = g(\xi)$  and  $r = \varphi$  (the positive eigenfunction

to the eigenvalue  $\lambda_1$ ), it is shown that there exists  $t_0 \in \mathbb{R}$  such that  $(P_t)$  has no solution for  $t > t_0$ , precisely one solution for  $t = t_0$ , and exactly two solutions for  $t < t_0$ , provided

$$0 < g'(-\infty) < \lambda_1 < g'(+\infty) < \lambda_2$$

and  $g$  is strictly convex.

3. Our theorem also sharpens a recent result of Hess and Ruf [5]. In that paper, for formally selfadjoint  $A$  and  $f$  of the form (1) with  $r = \varphi$ , it is assumed that

$$\lim_{\xi \rightarrow -\infty} \frac{g(x, \xi)}{\xi} = -\infty, \quad \lim_{\xi \rightarrow +\infty} \frac{g(x, \xi)}{\xi} > \lambda_1$$

(uniformly in  $x \in \bar{\Omega}$ ), and the existence of two constants  $T_1 \leq T_2$  is asserted such that problem  $(P_t)$  admits no solution for  $t > T_2$  and at least two solutions for  $t < T_1$  (perform the change of variable  $u \rightarrow -u$  in order to bring the problem considered in [5] to the present setting).

Since we rely on [6, Corollary 3.11], we suppose (as in [6]) that  $B$  is either the Dirichlet or the Neumann boundary operator. However, it is not difficult to verify that everything remains true if  $B$  is the boundary operator associated with the third BVP, i.e.

$$Bu = \frac{\partial u}{\partial \beta} + b_0 u,$$

where  $b_0 \geq 0$  and  $\beta$  is an outward pointing (nowhere tangent) smooth vectorfield on  $\partial\Omega$ .

## II. PROOF OF THE THEOREM

(a) It follows from [6, Corollary 3.11] that there exists a real number  $t_0$  such that  $(P_t)$  has no solution for  $t > t_0$  and at least one solution for  $t < t_0$ . Let  $t^* < t_0$  be fixed, and choose  $\tau \in (t^*, t_0)$ . Then there exists a smooth function  $\bar{u}$  such that

$$\begin{cases} A\bar{u} = f(x, \bar{u}; \tau) & \text{in } \Omega, \\ B\bar{u} = 0 & \text{on } \partial\Omega. \end{cases}$$

Since, by hypothesis (f2),  $f$  is strictly increasing in the variable  $t$ , it follows that  $\bar{u}$  is a strict supersolution for  $(P_{t^*})$ . By means of hypothesis (f3) and the arguments in [6, Lemma 2.7], we can find a strict subsolution  $\underline{u}$  of  $(P_{t^*})$  with  $B\underline{u} = 0$ , such that  $\underline{u} < \bar{u}$ .

(b) Let

$$\omega_0 := \max \{ |D_2 f(x, \xi; t^*)| : x \in \bar{\Omega}, \min \underline{u} \leq \xi \leq \max \bar{u} \},$$

and set

$$\omega := \max \{ \omega_0 + 1, \|a_0\|_{C(\bar{\Omega})} \}.$$

Moreover, let

$$F(u, t)(x) := f(x, u(x); t) + \omega u(x),$$

for all  $(x, t) \in \bar{\Omega} \times \mathbb{R}$  and all functions  $u: \bar{\Omega} \rightarrow \mathbb{R}$ , and denote by  $Kv$  the unique solution of the linear BVP

$$\begin{cases} (A + \omega)u = v & \text{in } \Omega, \\ Bu = 0 & \text{on } \partial\Omega. \end{cases}$$

Finally, let

$$E := C_B^1(\bar{\Omega}) := \{u \in C^1(\bar{\Omega}) : Bu = 0 \text{ on } \partial\Omega\},$$

equipped with the norm  $\|\cdot\|$  of  $C^1(\bar{\Omega})$ , and endow all function spaces with their natural order. Then it is well-known [e.g. 2, Section 4] that  $K: C(\bar{\Omega}) \rightarrow E$  is compact and strongly positive, and that problem  $(P_t)$  is equivalent to the fixed point equation

$$u = KF(u, t)$$

in  $E$ . The mapping

$$KF: E \times \mathbb{R} \rightarrow E$$

is continuous, and maps bounded sets into relatively compact sets. We note that

$$\underline{u} < KF(\underline{u}, t^*) \quad \text{and} \quad KF(\bar{u}, t^*) < \bar{u}, \quad (2)$$

and that  $K \mp(\cdot, t^*)$  is strongly increasing on the order interval

$$X := [\underline{u}, \bar{u}] := \{u \in E : \underline{u} \leq u \leq \bar{u}\}.$$

Since  $X$  is bounded in  $C(\bar{\Omega})$ , it follows that  $\overline{KF(X, t^*)}$  is compact in  $E$  [cf. 2, Section 9].

(c) Set  $G := KF(\cdot, t^*)$ . We want to show that  $G$  has at least two distinct fixed points. Since  $G$  is increasing, (2) implies that  $G(X) \subset X$ . Then, by Schauder's fixed point theorem,  $G$  has a fixed point  $u_0$  in  $X$ . Since  $G$  is strongly increasing, (2) further implies that  $X$  has nonempty interior  $\hat{X}$ , and that  $u_0 \in \hat{X}$ . Of course we can assume that  $u_0$  is the only fixed point of  $G$  in  $X$  (otherwise we are done). Then there exists  $\varepsilon > 0$  such that  $u_0 + \varepsilon \mathbb{B} \subset X$  (where  $\mathbb{B}$  is the open unit ball in  $E$ ), and such that the Leray–Schauder degree

$$\deg(id - G, u_0 + \varepsilon \mathbb{B}, 0)$$

is defined. By making use of the uniqueness of the Leray–Schauder degree and the permanence and excision properties of the fixed point index [cf. 2, Theorem (11.1) and the first formula in its proof], we find that

$$\begin{aligned} \deg(id - G, u_0 + \varepsilon \mathbb{B}, 0) &= i(G, u_0 + \varepsilon \mathbb{B}, E) \\ &= i(G, u_0 + \varepsilon \mathbb{B}, X) = i(G, X, X) = 1. \end{aligned} \quad (3)$$

Here the last equality is a trivial consequence of the convexity of  $X$  and the homotopy invariance property (cf. the proof of the Schauder fixed point theorem in [2, p. 660]).

(d) Suppose

$$\begin{cases} \text{there exists } \rho > 0 \text{ such that } u_0 + \varepsilon \mathbb{B} \subset \rho \mathbb{B} \text{ and} \\ KF(u, t) \neq u \text{ for all } t \in I := [t^*, t_0 + 1] \\ \text{and all } u \in E \text{ with } \|u\| = \rho. \end{cases} \quad (4)$$

Then, by the homotopy invariance of the Leray-Schauder degree,

$$\deg(id - G, \rho\mathbb{B}, 0) = \deg(id - KF(\cdot, t_0 + 1), \rho\mathbb{B}, 0) = 0,$$

since, according to the definition of  $t_0$ ,  $KF(\cdot, t_0 + 1)$  has no fixed point at all in  $E$ . Thus, by (3),

$$\deg(id - G, \rho\mathbb{B} \setminus (u_0 + \varepsilon\bar{\mathbb{B}}), 0) = \deg(id - G, \rho\mathbb{B}, 0) - \deg(id - G, u_0 + \varepsilon\bar{\mathbb{B}}, 0) = -1,$$

which implies that there is a fixed point of  $G$  in  $\rho\mathbb{B} \setminus (u_0 + \varepsilon\bar{\mathbb{B}})$ . Hence the existence of at least two distinct solutions of problem  $(P_*)$  is proved provided we verify the *a priori* estimate (4).

(e) Observe that  $K$  can be looked upon as a strongly positive compact endomorphism of  $E$ . Thus the spectral radius  $r(K)$  is positive and the only eigenvalue of  $K$  having a positive eigenvector [e.g. 2, Theorem (3.2)]. It follows that  $r(K) = (\lambda_1 + \omega)^{-1}$ .

Hypothesis (f3) implies that there exist numbers  $\mu < \lambda_1 + \omega$  and  $k \geq 0$  such that

$$F(u, t) \geq \mu u - k \quad (5)$$

for all  $u: \bar{\Omega} \rightarrow \mathbb{R}$  and all  $t \in I$ . Let  $w$  be the unique solution of the linear equation

$$w - \mu Kw = -kK\mathbb{1}.$$

Then (5) implies that

$$(u_t - w) - \mu K(u_t - w) \geq 0$$

for every fixed point  $u_t$  of  $KF(\cdot, t)$ ,  $t \in I$ . Consequently, since  $1/\mu > r(K)$ , [2, Theorem 3.2 (iv)] implies

$$u_t \geq w \quad \text{for every } t \in I. \quad (6)$$

Suppose now (4) is not true. Then we find sequences  $(t_j)$  in  $I$  and  $(u_j := u_{t_j})$  in  $E$  with  $\|u_j\| \rightarrow \infty$ , such that

$$u_j = KF(u_j, t_j) \quad (7)$$

for all  $j \in \mathbb{N}$ . Let  $v_j := u_j / \|u_j\|$  and observe that hypothesis (f4) and (6) imply that  $\{F(u_j, t_j) / \|u_j\| : j \in \mathbb{N}\}$  is bounded in  $C(\bar{\Omega})$ . Dividing (7) by  $\|u_j\|$  and using the compactness of  $K$  as a map from  $C(\bar{\Omega})$  to  $E$ , it follows that the sequence  $(v_j)$  is relatively compact in  $E$ . Hence, by passing to an appropriate subsequence, we may assume that

$$v_j \rightarrow v \quad \text{in } E$$

where, due to (6),

$$v \geq 0. \quad (8)$$

Hypothesis (f3) implies also the existence of numbers  $\alpha > 0$ ,  $\beta \geq 0$  such that

$$F(u, t) \geq (\lambda_1 + \omega + \alpha)u - \beta$$

for all  $u: \bar{\Omega} \rightarrow \mathbb{R}$  and all  $t \in I$ . Thus, by (7),

$$v_j \geq (\lambda_1 + \omega + \alpha)Kv_j - \|u_j\|^{-1}\beta K\mathbb{1},$$

and in the limit we get

$$v - (\lambda_1 + \omega + \alpha)Kv \geq 0.$$

Since  $(\lambda_1 + \omega + \alpha)^{-1} < r(K)$ , [2, Theorem 3.2 (iv)] and (8) imply  $v = 0$ . But this contradicts the obvious fact that  $\|v\| = 1$ .

(f) In order to prove that problem  $(P_t)$  admits a solution also for  $t = t_0$ , we take a sequence  $(t_j) \uparrow t_0$ . It then follows from part (e) of the present proof that corresponding solutions  $u_j$ :

$$u_j = KF(u_j, t_j) \quad (j \in \mathbb{N})$$

remain bounded in  $E$ . Next we observe that the sequence  $(u_j)$  is relatively compact in  $E$ ; for a suitable subsequence we have  $u_j \rightarrow u$  in  $E$  and  $u = KF(u, t_0)$ . Thus  $u$  is a solution of  $(P_{t_0})$ .  $\square$

### III. AN EXTENSION

An inspection of the above proof and the fact that there is no uniformity assumption with respect to  $t$  in the hypothesis of [6, Corollary 3.11] shows that the following more precise result is true.

**PROPOSITION.** *Suppose there exists a number  $T$  such that hypotheses (f3'') and (f4) hold only for  $t \geq T$ , and that the generalized limits in (f3) and (f4) are uniform only for  $t$  in bounded intervals of  $[T, +\infty)$ . Then there exists  $t_0 \in \mathbb{R}$  such that problem  $(P_t)$  has no solution for  $t > t_0$  and at least one solution for  $t < t_0$ . If  $t_0 > T$ , then  $(P_t)$  has at least two distinct solutions for  $T \leq t < t_0$  and at least one solution for  $t = t_0$ .*

The following example shows that this result is in some sense optimal, i.e. that in general we cannot expect two solutions for  $t < T$ .

**EXAMPLE.** Suppose  $f: \mathbb{R} \rightarrow \mathbb{R}^+$  is a smooth, increasing, strictly convex function satisfying

$$f'(-\infty) = 0 \quad \text{and} \quad \lambda_1 < f'(+\infty) < +\infty$$

(where  $\lambda_1 > 0$  is the first eigenvalue of  $-\Delta$ , subject to Dirichlet boundary conditions). Moreover, assume that

$$f(\xi) < \xi f'(\xi)$$

for sufficiently large  $\xi > 0$ . Consider the BVP

$$(A_t) \quad \begin{cases} -\Delta u = tf(u) & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases}$$

Then it follows from [6, Corollary 3.11] that there exists a  $t_0 \in \mathbb{R}$  such that  $(A_t)$  has no solution for  $t > t_0$  and at least one solution for  $t < t_0$ . Moreover, [2, Theorems (20.12) and (26.3)] imply that  $t_0 > 0$ , and that there exists a number  $t_\infty \in (0, t_0)$  such that  $(A_t)$  has at least two solutions for  $t_\infty < t < t_0$  and exactly one solution for  $t = t_0$  and  $t \in [0, t_\infty]$ . The monotonicity of  $f$  implies further that  $(A_t)$  has exactly one solution for  $t < 0$ . Finally,  $t_\infty$  is the principal eigenvalue of the linear

eigenvalue problem

$$\begin{cases} -\Delta u = \lambda f'(+\infty)u & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

i.e.  $t_\infty = \lambda_1/f'(+\infty)$ . Observe that, for every  $T > t_\infty$ , problem  $(A_T)$  satisfies the assumptions of the above Proposition, but not for  $T \leq t_\infty$ .

Lastly we remark that the Proposition generalizes [1, Theorem (7.6)], [cf. also 2, Section 21].

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*Note added in proof, 31 July 1979.* After this paper had been submitted for publication the authors became aware of an article by E. N. Dancer, On the ranges of certain weakly nonlinear elliptic partial differential equations, *J. Math. Pure Appl.* **57** (1978), 351–366. In that paper a similar result is proved by closely related considerations.

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